Dynamics and Control in Power Grids and Complex Oscillator Networks

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Electric Energy & Power Networks





- Electric energy is critical for our technological civilization
- Purpose of electric **power grid**: generate/transmit/distribute
- Op **challenges**: multiple scales, nonlinear, & complex

Trends, Advances, & Tomorrow's Power Grid



- Increasing renewables & deregulation
- growing demand & operation at capacity
- ⇒ increasing volatility & complexity, decreasing robustness margins

Rapid technological and scientific advances:

- **1** re-instrumentation: PMUs & FACTS
- complex & cyber-physical systems
- \Rightarrow cyber-coordination layer for smart grid



The Envisioned Power Grid complex, cyber-physical, & "smart" \Rightarrow smart grid keywords operation control & control monitorina \Rightarrow interdisciplinary: multi-scale power, control, comm, optimization physics optim, comp, physics, smar<mark>t grid</mark> complex distributed ... industry, & society dynamics nonlinear comp & comm smart \Rightarrow research themes: decentralized "understanding & cyber-physical taming complexity"

Outline

1 Introduction and motivation

• Project Samples in Complex Systems Control \cap Smart Grids

2 Synchronization in power networks & coupled oscillators

• Relating power networks and coupled oscillator models

3 Synchronization analysis & conditions

- Synchronization in a complete graph
- Synchronization in a sparse graph

4 Applications & experiments

- Comp & Opt: Power Flow Approximation
- Monitoring: Contingency Screening
- Distributed Control in Microgrids

5 Conclusions



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Project Samples II

3 Distributed wide-area control (with M. Jovanovic, M. Chertkov, & F. Bullo)

Inverters in microgrids (with J. Simpson-Porco, J.M. Guerrero, & F. Bullo)



Power Grids as Prototypical Complex Networks

 $\Rightarrow\,$ Similar challenges & tools in

Project Samples I

- biochemical reaction networks
- social networks & epidemics
- transportation networks
- robotic coordination & sensor ntkws
- \Rightarrow Plenty of synergies

and cross-fertilization



Outline



Mathematical Model of Power Transmission Network



Models of DC Sources with Inverters & Load Models

 DC source with droop-controlled DC/AC power converter [M.C. Chandorkar et. al. '93]:

$$D_i^{(\text{droop})}\dot{ heta}_i = P_i^{(\text{setpoint})} - \sum_j a_{ij}\sin(heta_i - heta_j)$$

 constant current and admittance loads in Kron-reduced network [F. Dörfler et al. '13]:

$$M_i \ddot{\theta}_i + D_i \dot{\theta}_i = P_i^{(\text{red})} - \sum_j a_{ij}^{(\text{red})} \sin(\theta_i - \theta_j)$$

• constant motor loads [P. Kundur '94]:

$$M_i \ddot{\theta}_i + D_i \dot{\theta}_i = P_i^{(\text{load})} - \sum_j a_{ij} \sin(\theta_i - \theta_j)$$



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Synchronization in Power Networks

Sync is crucial for the functionality and operation of the AC power grid. Generators have to swing in sync despite fluctuations/faults/contingencies.

Def:

- $\dot{\theta}_i = \dot{\theta}_j$ & $|\theta_i \theta_j|$ bounded \forall branches $\{i, j\}$
- = sync'd frequencies & constrained active power flows

Given: network parameters & topology and load & generation profile Q: " \exists an optimal, stable, and robust synchronous operating point ?"

- Security analysis [Araposthatis et al. '81, Wu et al. '80 & '82, Ilić '92, ...]
- 2 Load flow feasibility [Chiang et al. '90, Dobson '92, Lesieutre et al. '99, ...]
- Optimal generation dispatch [Lavaei et al. '12, Bose et al. '12, ...]
- Transient stability [Sastry et al. '80, Bergen et al. '81, Hill et al. '86, ...]
- S Inverters in microgrids [Chandorkar et. al. '93, Guerrero et al. '09, Zhong '11,...]

Synchronization in Complex Oscillator Networks

Pendulum clocks & "an odd kind of sympathy" [C. Huygens, Horologium Oscillatorium, 1673]

Today's canonical coupled oscillator model [A. Winfree '67, Y. Kuramoto '75]

Coupled oscillator model:

$$\dot{ heta}_i = \omega_i - \sum_{j=1}^n a_{ij} \sin(heta_i - heta_j)$$

- *n* oscillators with phase $\theta_i \in \mathbb{S}^1$
- **non-identical** natural frequencies $\omega_i \in \mathbb{R}^1$
- elastic **coupling** with strength $a_{ij} = a_{ji}$
- undirected & connected graph $G(\mathcal{V}, \mathcal{E}, A)$



Synchronization in Complex Oscillator Networks

applications

Coupled oscillator model:

$$\dot{ heta}_i = \omega_i - \sum_{j=1}^n a_{ij} \sin(heta_i - heta_j)$$



A few related applications:

- Sync in Josephson junctions [S. Watanabe et. al '97, K. Wiesenfeld et al. '98]
- Sync in a population of fireflies [G.B. Ermentrout '90, Y. Zhou et al. '06]
- Canonical model of coupled limit cycle oscillators [F.C. Hoppensteadt et al. '97, E. Brown et al. '04]
- Countless sync phenomena in sciences/bio/tech.
 [S. Strogatz '00, J. Acebrón '05 et al., F. Dörfler et al. '13]



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Synchronization in Complex Oscillator Networks phenomenology and challenges Synchronization is a trade-off: coupling vs. heterogeneity $\hat{\theta}_{i} = \omega_{i} - \sum_{j=1}^{n} a_{ij} \sin(\theta_{i} - \theta_{j})$ $\hat{\theta}_{i} = \omega_{i} - \sum_{j=1}^{n} a_{ij} \sin(\theta_{i} - \theta_{j})$ coupling small & $|\omega_{i} - \omega_{j}|$ large \Rightarrow incoherence \Rightarrow frequency sync

A central question: quantify "coupling" vs. "heterogeneity" [S. Strogatz '01, A. Arenas et al. '08, S. Boccaletti et al. '06]

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Applications & experiments

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- Distributed Control in Microgrids
- 5 Conclusions

Relating power networks and coupled oscillator models

(1) Power network model:

$$egin{aligned} M_i\ddot{ heta}_i + D_i\dot{ heta}_i &= P_i - \sum_j a_{ij}\sin(heta_i - heta_j) \ D_i\dot{ heta}_i &= P_i - \sum_j a_{ij}\sin(heta_i - heta_j) \end{aligned}$$

(2.1) Variation of coupled oscillator model:

$$\dot{ heta}_i = extsf{P}_i - \sum_j extsf{a}_{ij} \sin(heta_i - heta_j)$$

(2.2) Add decoupled frequency dynamics:

 $\ddot{\theta}_i = -\dot{\theta}_i$

Homotopy: construct continuous interpolation between (1) and (2)



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Relating power networks and coupled oscillator models main result

Family of dynamical system \mathcal{H}_{λ} :

$$\frac{d}{dt} \begin{bmatrix} \theta \\ \dot{\theta} \end{bmatrix} = (1 - \lambda) \cdot (1) + \lambda \cdot (2), \qquad \lambda \in [0, 1]$$

Theorem: Properties of the \mathcal{H}_{λ} family [F. Dörfler & F. Bullo '11]

() Invariance of equilibria: For all $\lambda \in [0, 1]$ the equilibria are

$$\left\{\left(\theta,\dot{\theta}\right):\,\dot{\theta}_{i}=0\;,\;P_{i}=\sum_{j}a_{ij}\sin(\theta_{i}-\theta_{j})
ight\}.$$

② Invariance of local stability: For all equilibria and $\lambda \in [0, 1]$, the Jacobian has constant number of stable/unstable/zero eigenvalues.

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Synchronization in a Complete & Homogeneous Graph

Classic Kuramoto model: [Y. Kuramoto '75]

$$\dot{\theta}_i = \omega_i - \frac{K}{n} \sum_{j=1}^n \sin(\theta_i - \theta_j)$$

Theorem: Explicit sync condition

[F. Dörfler & F. Bullo '11]

The following statements are equivalent:

- Coupling dominates heterogeneity, i.e., $|K > K_{\text{critical}} \triangleq \omega_{\text{max}} \omega_{\text{min}}|$.
- **2** Kuramoto models with $\{\omega_1, \ldots, \omega_n\} \subseteq [\omega_{\min}, \omega_{\max}]$ synchronize.

Strictly improves existing cond's [F. de Smet et al. '07, N. Chopra et al. '09, G. Schmidt et al. '09, A. Jadbabaie et al. '04, S.J. Chung et al. '10, J.L. van Hemmen et al. '93, A. Franci et al. '10, S.Y. Ha et al. '10, G.B. Ermentrout '85, A. Acebron et al. '00]

Synchronization in a Complete & Homogeneous Graph main proof ideas

• Arc invariance: $\theta(t)$ in γ arc \Leftrightarrow arc-length $V(\theta(t))$ is non-increasing



Synchronization in a Complete & Homogeneous Graph main proof ideas

Q Arc invariance: $\theta(t)$ in γ arc \Leftrightarrow arc-length $V(\theta(t))$ is non-increasing

$$\Leftrightarrow \begin{cases} V(\theta(t)) = \max_{i,j \in \{1,...,n\}} |\theta_i(t) - \theta_j(t)| \\ D^+ V(\theta(t)) \le 0 \end{cases}$$

true if $K \sin(\gamma) \ge K_{critical}$

② Frequency synchronization ⇔ linear time-varying system (consensus)

$$rac{d}{dt}\dot{ heta}_i = -\sum_{j=1}^n {f a}_{ij}(t)\left(\dot{ heta}_i - \dot{ heta}_j
ight),$$

where $a_{ij}(t) = \frac{K}{n} \cos(\theta_i(t) - \theta_j(t))$ becomes positive in finite time

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Primer on Algebraic Graph Theory

Laplacian matrix L = "degree matrix" – "adjacency matrix"

$$L = L^{T} = \begin{bmatrix} \vdots & \ddots & \vdots & \ddots & \vdots \\ -a_{i1} & \cdots & \sum_{j=1}^{n} a_{ij} & \cdots & -a_{in} \\ \vdots & \ddots & \vdots & \ddots & \vdots \end{bmatrix} \ge 0$$

Notions of connectivity

- spectral: 2nd smallest eigenvalue of L is "algebraic connectivity" $\lambda_2(L)$
- topological: degree $\sum_{j=1}^{n} a_{ij}$ or degree distribution

Notions of heterogeneity

 $\|\omega\|_{\mathcal{E},\infty} = \max_{\{i,j\}\in\mathcal{E}} |\omega_i - \omega_j| \leq \varepsilon$

$$\omega_j|, \qquad \|\omega\|_{\mathcal{E},2} = \left(\sum_{\{i,j\}\in\mathcal{E}} |\omega_i - \omega_j|^2\right)^{1/2}$$

Synchronization in Sparse Graphs a brief overview

$$\dot{\theta}_{i} = \omega_{i} - \sum_{j=1}^{n} a_{ij} \sin(\theta_{i} - \theta_{j})$$
a necessary sync condition:
$$\sum_{j=1}^{n} a_{ij} \ge |\omega_{i}| \quad \Leftarrow \quad \text{sync}$$
[C. Tavora and O.J.M. Smith '72]
a sufficient sync condition:
$$\lambda_{2}(L) > ||\omega||_{\mathcal{E},2} \quad \Rightarrow \quad \text{sync}$$
[F. Dörfler and F. Bullo '12]
$$\Rightarrow \quad \exists \text{ similar conditions with diff. metrics on coupling & heterogeneity}$$

$$\Rightarrow \quad \textbf{Problem: sharpest general conditions are conservative}$$

A Nearly Exact Synchronization Condition

Theorem: Sharp sync condition [F. Dörfler, M. Chertkov, & F. Bullo '12]

Under one of following assumptions:

- 1) extremal topologies: trees, homogeneous graphs, or $\{3,4\}$ rings
- 2) extremal parameters: $L^{\dagger}\omega$ is bipolar, small, or symmetric (for rings)
- 3) arbitrary one-connected combinations of 1) and 2)
- If $\|L^{\dagger}\omega\|_{\mathcal{E},\infty} < 1$

 $\Rightarrow \exists \text{ a unique \& locally exponentially stable synchronous solution} \\ \theta^* \in \mathbb{T}^n \text{ satisfying } |\theta^*_i - \theta^*_j| \leq \arcsin(\|L^{\dagger}\omega\|_{\mathcal{E},\infty}) \text{ for all } \{i,j\} \in \mathcal{E}$

... and result is "statistically correct" .

A Nearly Exact Synchronization Condition statistical accuracy for power networks

Randomized power network test cases

with 50 % randomized loads and 33 % randomized generation

Randomized test case	Numerical worst-case	Analytic prediction of	Accuracy of condition:
(1000 instances)	angle differences:	angle differences:	$\operatorname{arcsin}(\ L^{\dagger}\omega\ _{\mathcal{E},\infty})$
	$\max_{\substack{\{i,j\}\in\mathcal{E}}} \theta_i^*-\theta_j^* $	$\operatorname{arcsin}(\ L^{\dagger}\omega\ _{\mathcal{E},\infty})$	$-\max_{\{i,j\}\in\mathcal{E}} \theta_i^*-\theta_j^* $
9 bus system	0.12889 rad	0.12893 rad	$4.1218 \cdot 10^{-5}$ rad
IEEE 14 bus system	0.16622 rad	0.16650 rad	$2.7995 \cdot 10^{-4}$ rad
IEEE RTS 24	0.22309 rad	0.22480 rad	$1.7089 \cdot 10^{-3}$ rad
IEEE 30 bus system	0.16430 rad	0.16456 rad	$2.6140 \cdot 10^{-4}$ rad
New England 39	0.16821 rad	0.16828 rad	$6.6355 \cdot 10^{-5}$ rad
IEEE 57 bus system	0.20295 rad	0.22358 rad	$2.0630 \cdot 10^{-2}$ rad
IEEE RTS 96	0.24593 rad	0.24854 rad	$2.6076 \cdot 10^{-3}$ rad
IEEE 118 bus system	0.23524 rad	0.23584 rad	$5.9959 \cdot 10^{-4}$ rad
IEEE 300 bus system	0.43204 rad	0.43257 rad	$5.2618 \cdot 10^{-4}$ rad
Polish 2383 bus system (winter peak 1999/2000)	0.25144 rad	0.25566 rad	$4.2183 \cdot 10^{-3}$ rad

 \Rightarrow similar results have been reproduced by **SIEMENS**



A Nearly Exact Synchronization Condition

- Monte Carlo studies: for range of random topologies & parameters
- \Rightarrow with high prob & accuracy: sync "for almost all" $G(\mathcal{V}, \mathcal{E}, A) \& \omega$
- Possibly thin sets of degenerate counter-examples for large rings

Power Flow Approximation

AC power flow: $P_i = \sum_{j=1}^n a_{ij} \sin(\theta_i - \theta_j)$ DC power flow: $P_i = \sum_{j=1}^n a_{ij} (\delta_i - \delta_j)$ Conventional DC approximation: $\theta_i^* - \theta_j^* \approx \delta_i^* - \delta_j^*$ Our modified DC approximation: $\theta_i^* - \theta_j^* \approx \arcsin(\delta_i^* - \delta_j^*)$ $\int_{0}^{0} \frac{1}{\theta_i^*} - \frac{1}{\theta_i^*} \frac$

Outline



Power Flow Approximation Security-Constrained Power Flow			
AC power flow with security constraints			
$P_i = \sum_{j=1}^n a_{ij} \sin(heta_i - heta_j), \qquad heta_i - heta_j < \gamma_{ij} orall \{i, j\} \in \mathcal{E}$			
DC power flow with security constraints			
${{P}_{i}}=\sum_{j=1}^{n}{{{a}_{ij}}{\left({{\delta _{i}}-{\delta _{j}}} ight)}},\qquad \left {{\delta _{i}}-{\delta _{j}}} ight <{\gamma _{ij}} orall\left\{ {i,j} ight\}\in \mathcal{E}$			
Novel test			
${\mathcal{P}}_i = \sum_{j=1}^n {a}_{ij} (\delta_i - \delta_j) , \qquad \delta_i - \delta_j < \sin(\gamma_{ij}) orall \left\{ i, j ight\} \in {\mathcal{E}}$			
Proof of equivalence for a tree: $\theta_i^* - \theta_j^* = \arcsin(\delta_i^* - \delta_j^*)$			

Contingency Analysis



IEEE Reliability Test System '96 at nominal operating point

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two contingencies





Distributed Averaging PI Droop Control in Microgrids design based on coupled oscillator insights

Microgrid modeled as network of loads and inverters Distributed & Averaging PI droop-controller (DAPI)



Decentralized primary control \Rightarrow sync: $\dot{ heta}_i(t) \rightarrow \omega_{
m sync}$



Distributed secondary control \Rightarrow frequency regulation: $\omega_{sync} \rightarrow 0$

Distributed Averaging PI Droop Control in Microgrids

Theorem (Properties DAPI control) [J. Simpson-Porco, F. Dörfler, & F. Bullo, '12]

- unique & exponentially stable closed-loop sync manifold;
- frequency regulation
 & optimal power sharing;
- robustness to voltage variations, losses, & uncertainties;
- plug'n'play & arbitrary tuning.

 $\begin{array}{|c|c|c|c|c|c|c|}\hline \textbf{Microgrid} \\ P_1 & P_2 & P_{|\mathcal{V}_I|} & \theta_{|\mathcal{V}_I|} \\ \hline P_1 & p_1 & P_2 & P_{|\mathcal{V}_I|} & P_{|\mathcal{V}_I|} \\ \hline P_1 & \dot{\theta}_2 & p_2 & \dot{\theta}_{|\mathcal{V}_I|} & p_{|\mathcal{V}_I|} \\ \hline \textbf{Secondary} & P_2 & \textbf{Secondary} & \textbf{Secondary} \\ \hline \end{array}$

PI droop-controller (DAPI)

Distributed & **A**veraging

Distributed Averaging PI Droop Control in Microgrids Practical implementation at Aalborg University, Denmark

Implementation (together with Q. Shafiee & J.M. Guerrero)





Experimental results are remarkable: off-the-shelf, robust, small transients 29/30



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Summary

Lessons learned today:

- power networks are coupled oscillators
- sync if "coupling > heterogeneity"
- necessary, sufficient, & sharp sync cond's
- theory is useful, robust & applicable

Further results & applications (not shown)

Related ongoing and future work:

- more complete theory & more detailed models
- from analysis to control synthesis: cont. control design, hybrid remedial action schemes, computation & optimization





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Related Publications

- F. Dörfler and F. Bullo.Synchronization in Complex Oscillator Networks: A Survey. In Automatica, April 2013, Note: submitted.
- 1 F. Dörfler, M. Chertkov, and F. Bullo. Synchronization in Complex Oscillator Networks and Smart Grids. In Proceedings of the National Academy of Sciences, February 2013.
- F. Dörfler, F. Pasqualetti and F. Bullo. Continuous-Time Distributed Observers with Discrete Communication. In IEEE Journal of Selected Topics in Signal Processing, March 2013.
- J.W. Simpson-Porco, F. Dörfler, and F. Bullo. Synchronization and Power-Sharing for Droop-Controlled Inverters in Islanded Microgrids. In Automatica, Februay 2013, Note: provisionally accepted.
- F. Dörfler and F. Bullo. Kron Reduction of Graphs with Applications to Electrical Networks. In IEEE Transactions on Circuits and Systems I., January 2013.
- F. Pasqualetti, F. Dörfler, and F. Bullo. Attack Detection and Identification in Cyber-Physical Systems. In IEEE Transactions on Automatic Control, December 2012, Note: to appear.
- F. Dörfler and F. Bullo. Synchronization and Transient Stability in Power Networks and Non-uniform Kuramoto Oscillators. In SIAM Journal on Control and Optimization, June 2012.
- F. Dörfler and F. Bullo. On the Critical Coupling for Kuramoto Oscillators. In SIAM Journal on Applied Dynamical Systems, September 2011.

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